

# **STATS 207: Time Series Analysis**

## **Autumn 2020**

Lectures 5-6: ARMA/ARIMA Modelling

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- Homework assignment due Monday 10/5/2020.
- Office hours 11:20-12:20 after the lecture.

ACF of ARMA Models

Forecasting

ESTIMATING **ARMA** PARAMETERS

## Midway Summary

- **AR( $p$ )** :

$$x_t = \phi_1 x_{t-1} + \dots + \phi_{t-p} x_p + w_t \quad \text{or} \quad \phi(B)x_t = w_t,$$

where  $\phi(z)$  is the **autoregressive polynomial**

$$\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p.$$

- **MA( $q$ )**:

$$x_t = w_t + \theta_1 w_{t-1} + \dots + \theta_q w_{t-q}, \quad \text{or} \quad x_t = \theta(B)w_t,$$

where  $\theta(z)$  is the **moving average polynomial**

$$\theta(z) = 1 + \theta_1 z + \dots + \theta_q z^p.$$

- **ARMA( $p, q$ )**

$$x_t = \phi_1 x_{t-1} + \dots + \phi_{t-p} x_p + w_t + \theta_1 w_{t-1} + \dots + \theta_q w_{t-q}$$

or

$$\phi(B)x_t = \theta(B)w_t.$$

# Causality and MA Representation

- **Definition:** **ARMA**( $p, q$ ) model is called **causal** if

$$x_t = \sum_{j=0}^{\infty} \psi_j w_{t-j} = \psi(B)w_t,$$

where:

- $(w_t)$  is white noise,
  - $\sum_{j=0}^{\infty} |\psi_j| < \infty$ ,
  - $\psi_0 = 1$ ,
  - $\psi(B) \equiv \sum_{j=0}^{\infty} \psi_j B^j$ .
- $\psi(B)$  gives an **infinite-order MA representation**.
  - **Example:** The **AR**(1) process is causal iff  $|\phi| < 1$ . Equivalently, it is causal iff the magnitude of the root of  $\phi(z) = 1 - \phi z$  is bigger than 1. More generally...

# Causality of ARMA

- **Property:** An **ARMA**( $p, q$ ) model is causal iff  $\phi(z) \neq 0$  for  $|z| \leq 1$ .  
In this case,

$$\psi(z) = \sum_{j=0}^{\infty} \psi_j z^j = \frac{\theta(z)}{\phi(z)}, \quad |z| \leq 1.$$

“ARMA is causal if  $\phi(z)$  has no roots inside the unit circle.”

- **Example 3.8:**

$$x_t = 0.9x_{t-1} + w_t + 0.5w_{t-1}$$

$$\phi(z) = 1 - 0.9z$$

$$\theta(z) = 1 + 0.5z$$

The MA representation of  $x_t$  is obtained from  $\phi(z)\psi(z) = \theta(z)$ :

$$(1 - 0.9z)(1 + \psi_1 z + \dots + \psi_j z^j + \dots) = 1 + 0.5z$$

$$1 + (\psi_1 - 0.9)z + (\psi_2 - 0.9\psi_1)z^2 + \dots + (\psi_j - 0.9\psi_{j-1})z^j + \dots = 1 + 0.5z$$

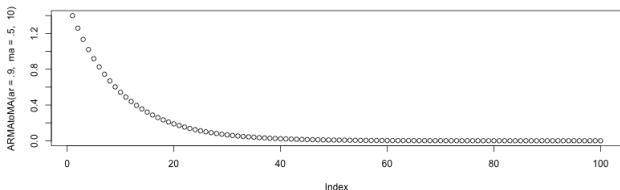
By matching coefficients:

$$x_t = w_t + 1.4 \sum_{j=1}^{\infty} 0.9^{j-1} w_{t-j}.$$

## Using R (Example 3.8)

```
ARMAtoMA(ar = .9, ma = .5, 10) # first 10 psi-weights
```

```
1.4 1.26 1.134 1.0206 0.91854 0.826686 0.7440174 ...
```



**Example:** Textbook conditions for causality of **AR(2)** (Example 3.9):

$$\phi_1 + \phi_2 < 1, \quad \phi_2 - \phi_1 < 1, \quad \text{and} \quad |\phi_2| < 1.$$

No **simple** conditions for causality in the general case.

## Example 3.11: AR with complex roots

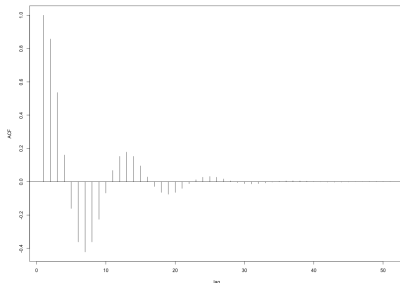
$$x_t = 1.5x_{t-1} - 0.75x_{t-2} + w_t, \quad \sigma_w^2 = 1.$$

$$\phi(z) = 1 - 1.5z + 0.75z^2 = (1 - \sqrt{-1/3} - z)(1 + \sqrt{-1/3} - z).$$

```
z = c(1, -1.5, .75) # coefficients of the polynomial
polyroot(z) # print roots
```

```
1+0.57735026918963i 1-0.57735026918963i
```

```
ACF = ARMAacf(ar=c(1.5, -.75), ma=0, 50)
plot(ACF, type="h", xlab="lag")
abline(h=0)
```





## Invertibility and AR Representation

- **Definition:** An **ARMA**( $p, q$ ) model is said to be **invertible** if  $(x_t)$  can be written as

$$\pi(B)x_t = \sum_{j=0}^{\infty} \pi_j x_{t-j} = w_t,$$

where

- $\pi(b) = \sum_{j=0}^{\infty} \pi_j B^j$
  - $\sum_{j=0}^{\infty} |\pi_j| < \infty$ .
  - $\pi_0 = 1$
- **Property:** An **ARMA**( $p, q$ ) model is invertible iff  $\theta(z) \neq 0$  for  $|z| \leq 1$ . In this case,

$$\pi(z) = \sum_{j=0}^{\infty} \pi_j z^j = \frac{\phi(z)}{\theta(z)}, \quad |z| \leq 1.$$

“ARMA is invertible iff  $\theta(z)$  has no roots inside the unit circle.”

## Example 3.8 (cont'd)

- Example (Example 3.8):

$$x_t = 0.9x_{t-1} + 0.5w_{t-1} + w_t.$$

- We have:  $\phi(z) = 1 - 0.9z$ ,  $\theta(z) = 1 + 0.5z$ .
- Invertible representation:

$$\theta(z)\pi(z) = \phi(z)$$

$$(1 + 0.5z)(1 + \pi_1z + \pi_2z^2 + \dots) = 1 - 0.9z.$$

We get:  $\pi_j = (-1)^j 1.4(0.5)^{j-1}$ ,  $j \geq 1$ , hence

$$x_t = 1.4 \sum_{j=1}^{\infty} (-0.5)^{j-1} x_{t-j} + w_t.$$

- Using R:

```
ARMAtoAR(ar = .9, ma = .5, 8) # first 8 pi-weights
```

```
-1.4 0.7 -0.35 0.175 -0.0875 0.04375 -0.021875 0.0109375
```

- **Prediction is easy** for processes with AR representation

$$x_t = \sum_{j=1}^{\infty} a_j x_{t-j} + w_t, \quad \sum_{j=0}^{\infty} |a_j| < \infty.$$

- Indeed, if  $(w_t)$  is iid noise,

$$\mathbb{E}[x_{t+1} | x_t, x_{t-1}, \dots] = \sum_{j=1}^{\infty} a_j x_{t-j-1} = \sum_{j=0}^{\infty} a_{j+1} x_{t-j}.$$

- **Property:** Existence of such representation for **stationary ARMA processes** is equivalent to **invertibility**.

## $\pi$ and Prediction (cont'd)

- **Property:** Existence of such representation for **stationary ARMA processes** is equivalent to **invertibility**.

**Proof:** Rewrite

$$x_t - \sum_{j=1}^{\infty} a_j x_{t-j} = \pi(B)x_t = w_t,$$

where  $\pi_0 = 1$ ,  $\pi_j = -a_j$ ,  $j \geq 1$ .

- **Consequence:** **Given** the invertibility relation

$$\pi(B)x_t = w_t,$$

we can predict using the **weights embedded** in  $\pi$ :

$$x_{t+1}^t = - \sum_{j=0} \pi_{j+1} x_{t-j}$$

## AR and MA Polynomials – Recap

Assume **causality** and **invertibility** of **ARMA**( $p, q$ )

- At the **process** level:

$$w_t = \pi(B)x_t \quad \text{and} \quad \psi(B)w_t = x_t.$$

- At **operator** level

$$\pi(B)\psi(B) = I.$$

- At level of **power/Laurent series**

$$\pi(z)\psi(z) = 1, \quad |z| \leq 1.$$

- Causal linear process representation

$$x_t = \sum_{j=0}^{\infty} \psi_j w_{t-j}$$

- **Autocovariance**

$$\gamma(h) = \sigma_w^2 \sum_{t=0}^{\infty} \psi_t \psi_{t+h}, \quad h \geq 0,$$

(sliding window/convolution interpretation)

- **Special case: MA(q) process** ( $\psi_j = \theta_j$ , for  $j = 0, \dots, h$ )

$$\gamma(h) = \sigma_w^2 \sum_{j=0}^{q-h} \theta_j \theta_{j+h}, \quad 0 \leq h \leq q.$$

- **Very special case: MA(1),  $\sigma_w^2 = 1$ ,**

$$\gamma(h) = \begin{cases} 1 + \theta^2 & h = 0, \\ \theta & h = \pm 1, \\ 0 & \text{otherwise.} \end{cases}$$

- Linear **Difference Equation** for ACF

$$\gamma(h) = \sum_{i=1} \phi_i \gamma(h-i), \quad h \geq \max(p, q+1),$$

with **initial conditions**

$$\gamma(h) = \sum_{j=1}^p \phi_j \gamma(h-j) + \sigma_w^2 \sum_{j=h}^q \theta_j \psi_{j-h}, \quad 0 \leq h < \max(p, q+1).$$

- See Chapter 3.2 for solving linear difference equations.

## ACF of ARMA(1,1) (Example 3.11)

Example 3.11:

$$x_t = \phi x_{t-1} + \theta w_{t-1} + w_t, \quad |\phi| < 1.$$

The autocovariance satisfies

$$\gamma_x(h) = \phi \gamma_x(h-1), \quad h \geq 2,$$

with initial condition:

$$\gamma_x(1) = \phi \gamma_x(0) + \sigma_w^2 \theta, \quad \text{and} \quad \gamma_x(0) = \phi \gamma_x(-1) + \sigma_w^2 (1 + \theta \phi + \theta^2).$$

Solving for  $\gamma_x(0)$  and  $\gamma_x(1) = \gamma_x(-1)$ :

$$\gamma_x(0) = \sigma_w^2 \frac{1 + 2\theta\phi + \theta^2}{1 - \phi^2}, \quad \gamma_x(1) = \sigma_w^2 \frac{(1 + \theta\phi)(\phi + \theta)}{1 - \phi^2}.$$

From here,

$$\gamma_x(h) = \sigma_w^2 \frac{(1 + \theta\phi)(\phi + \theta)}{1 - \phi^2} \phi^{h-1}, \quad h \geq 1.$$

**Note:** ACF of ARMA(1,1) is of the **same form as the ACF of AR(1)**.

To distinguish the two, we introduce Partial ACF.



- **Definition: Partial Correlation**

$$\begin{aligned} \text{ParCorr}(X, Y | Z_1, \dots, Z_h) \\ = \text{Corr} \left( X - \hat{X}(Z_1, \dots, Z_h), Y - \hat{Y}(Z_1, \dots, Z_h) \right) \end{aligned}$$

Meaning: Linear relationship between  $X$  and  $Y$  that **cannot be attributed** to  $Z_1, \dots, Z_h$ .

- **Definition:** The **partial ACF** (PACF) of a stationary process  $x_t$

$$\phi_{hh} \equiv \text{ParCorr}(x_{t+h}, x_t | x_{t+1}, \dots, x_{t+h-1}),$$

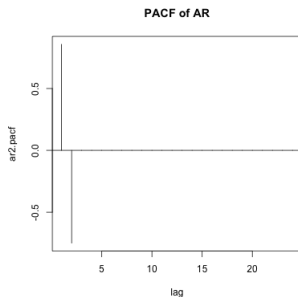
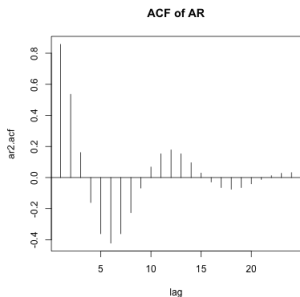
where  $\hat{X}(Z_1, \dots, Z_h)$  is the regression of  $X$  on  $Z_1, \dots, Z_h$ .

Meaning: Linear relationship between two lagged values that **cannot be attributed** to shorter lags.

## Example – Partial ACF of AR

**Example 3.16:**  $x_t = 1.5x_{t-1} - 0.75x_{t-2} + w_t$

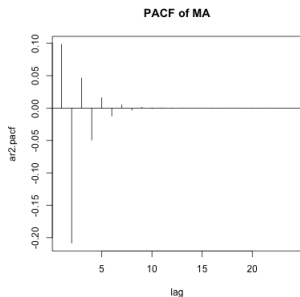
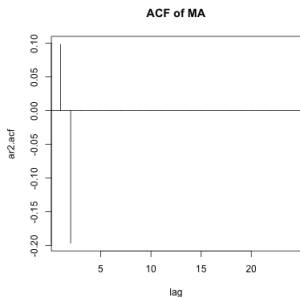
```
ar2.acf = ARMAacf(ar=c(1.5,-.75), ma=0, 24)[-1]
ar2.pacf = ARMAacf(ar=c(1.5,-.75), ma=0, 24, pacf=TRUE)
par(mfrow=c(1,2))
plot(ar2.acf, type="h", xlab="lag", main="ACF of AR")
abline(h=0)
plot(ar2.pacf, type="h", xlab="lag", main="PACF of AR")
abline(h=0)
```



## Example – Partial ACF of MA

**Example:**  $x_t = w_t + 1.5w_{t-1} - 0.75w_{t-2}$

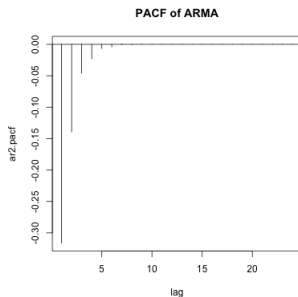
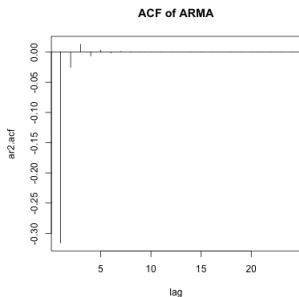
```
ar2.acf = ARMAacf(ar=0,ma=c(1.5,-.75), 24)[-1]
ar2.pacf = ARMAacf(ar=0, ma=c(1.5,-.75), 24, pacf=TRUE)
par(mfrow=c(1,2))
plot(ar2.acf, type="h", xlab="lag", main="ACF of MA")
abline(h=0)
plot(ar2.pacf, type="h", xlab="lag", main="PACF of MA")
abline(h=0)
```



## Example – Partial ACF of ARMA

**Example:**  $x_t = -0.5x_{t-1} + w_t + 1.5w_{t-1} - 0.75w_{t-2}$

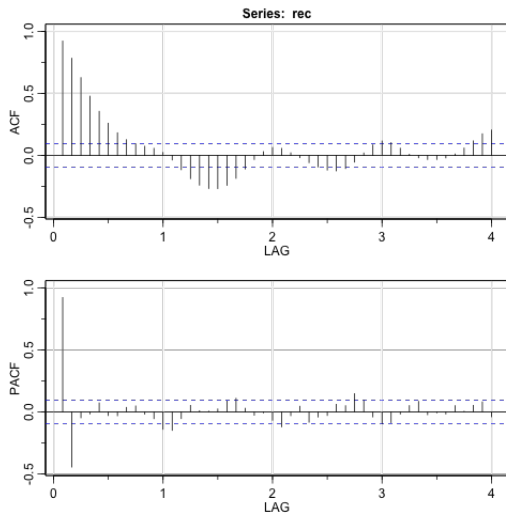
```
ar2.acf = ARMAacf(ar = -0.5, ma=c(1.5,-.75), 24)[-1]
ar2.pacf = ARMAacf(ar= -0.5, ma=c(1.5,-.75), 24, pacf=TRUE)
par(mfrow=c(1,2))
plot(ar2.acf, type="h", xlab="lag", main="ACF of ARMA")
abline(h=0)
plot(ar2.pacf, type="h", xlab="lag", main="PACF of ARMA")
abline(h=0)
```



## Contrasting the PACF and ACF

	<b>AR(p)</b>	<b>MA(q)</b>	<b>ARMA(p,q)</b>
ACF	Decays	Cutoff $q$	Decays
PACF	Cutoff $p$	Decays	Decays

## Example – ACF and PACF of Recruitment Data



- Looks like **AR(2)**!

## Example – PACF and OLS

Fit an **AR(2)**:

$$x_t = \phi_1 x_{t-1} + \phi_2 x_{t-2} + w_t.$$

```
(regr = ar.ols(rec, order=2, demean=F, intercept=TRUE)) # regression  
regr$asy.se.coef # standard errors
```

(fitting using the OLS method, more details later)

```
Call:  
ar.ols(x = rec, order.max = 2, demean = F, intercept = TRUE)  
  
Coefficients:  
      1      2  
1.3541 -0.4632  
  
Intercept: 6.737 (1.111)  
  
Order selected 2  sigma^2 estimated as 89.72  
$x.mean  
1.11059887598347  
$ar  
0.0417890066543078 0.0418794219793683
```

# Forecasting I – Definitions

- The **best**  $m$ -step ahead predictor

$$x_{n+m}^{n,\dagger} = \mathbb{E} [x_{n+m} | x_1, \dots, x_n]$$

minimizes the mean-squared error

$$P_{n+m}^n = \mathbb{E} [(x_{n+m} - x_{n+m}^n)^2].$$

- Definition: Linear predictor**,  $m$ -step ahead, from data  $x_1, \dots, x_n$ ,

$$x_{n+m}^n \equiv x_{n+m}^n(\alpha_1, \dots, \alpha_n) = \mu + \sum_{k=1}^n \alpha_k (x_k - \mu).$$

- Simplification:** Assume  $\mu = 0$ .
- Definition: Best linear predictor:**

$$x_{n+m}^{n,*} \equiv x_{n+m}^n(\alpha_{n+m,1}^{n,*}, \dots, \alpha_{n+m,n}^{n,*}) = \sum_{k=1}^n \alpha_{n+m,k}^{n,*} x_k,$$

where

$$(\alpha_{n+m,1}^{n,*}, \alpha_{n+m,2}^{n,*}, \dots, \alpha_{n+m,n}^{n,*}) \equiv \operatorname{argmin}_{(\alpha_1, \dots, \alpha_n) \in \mathbb{R}^n} P_{n+m}^n (x_{n+m}^n(\alpha_1, \dots, \alpha_n)).$$



## Forecasting II – Deriving the Best Linear Predictor

- (1) Express mean-squared estimation error using variances  
(recall  $\text{Cov}(X, Y) = \mathbb{E}[XY]$  if  $\mathbb{E}[X] = 0$ ):

$$\begin{aligned} P_{n+m}^n &= \text{Var}(x_{n+m} - x_{n+m}^n) \\ &= \text{Var}(x_{n+m}) - 2\text{Cov}\left[x_{n+m} \sum_{k=1}^n \alpha_{n+m,k}^n x_k\right] + \text{Var}\left(\sum_{k=1}^n \alpha_{n+m,k}^n x_k\right) \end{aligned}$$

- (2) Evaluate covariances using matrices/vectors:

$$\text{Var}\left(\sum_{k=1}^n \alpha_{n+m,k}^n x_k\right) = \boldsymbol{\alpha}' \boldsymbol{\Gamma}_n \boldsymbol{\alpha}, \quad (\boldsymbol{\alpha})_k = \alpha_{n+m,k}^n, \quad (\boldsymbol{\Gamma}_n)_{ij} = \mathbb{E}[x_i x_j]$$

$$\text{Cov}\left[x_{n+m} \sum_{k=1}^n \alpha_{n+m,k}^n x_k\right] = \boldsymbol{\gamma}'_{n+m} \boldsymbol{\alpha}, \quad (\boldsymbol{\gamma}_{n+m})_k = \mathbb{E}[x_{n+m} x_k].$$

- (3) LS solution:

$$\boldsymbol{\alpha}_{n+m}^{n,*} \equiv \boldsymbol{\alpha}^* \equiv \underset{\boldsymbol{\alpha}}{\text{argmin}} \left( \boldsymbol{\alpha}' \boldsymbol{\Gamma}_n \boldsymbol{\alpha} - 2 \boldsymbol{\gamma}'_{n+m} \boldsymbol{\alpha} \right)$$

$$\boldsymbol{\Gamma}_n \boldsymbol{\alpha}_{n+m}^{n,*} = \boldsymbol{\gamma}_{n+m}^n.$$

## Forecasting II' - Alternative Derivation

(3') Alternative derivation:

- **Property 3.3** (“orthogonality principle”)  $x_{n+m}^n$  is the best linear predictor based on  $x_1, \dots, x_n$  iff

$$\mathbb{E}[(x_{n+m} - x_{n+m}^n)x_k] = 0, \quad k = 1, \dots, n$$

(proof by the Projection Theorem in B.1)

- Consequently,  $\alpha_{n+m,1}^{n,*}, \dots, \alpha_{n+m,n}^{n,*}$  must satisfy

$$\begin{aligned}\mathbb{E}[x_{n+m}x_k] &= \mathbb{E}[x_{n+m}^n x_k] \\ (\gamma_{n+m}^n)_k &= \sum_{j=1}^n \alpha_{n+m,j}^{n,*} \mathbb{E}[x_j x_k]\end{aligned}$$

for all  $k = 1, \dots, n$ .

- In vector notation:

$$\gamma_{n+m}^n = \Gamma_n \alpha_{n+m}^{n,*}.$$

## Forecasting III – Under Stationarity

- If  $x_t$  is stationary

$$(\Gamma_n)_{ij} = \mathbb{E}[x_i x_j] = \gamma_x(i - j), \quad (\text{Toeplitz, non-negative definite})$$

$$(\gamma_{n+m}^n)_k = \mathbb{E}[x_{n+m} x_k] = \gamma_x(n + m - k).$$

- **Example:** One-step ahead prediction

$$\Gamma_n \alpha_{n+1}^{n,*} = \gamma_{n+1}^n.$$

Prediction error satisfies

$$P_{n+1}^n \equiv \mathbb{E}[(x_{n+1} - x_{n+1}^1)^2] = \gamma_x(0) - \gamma_{n+1}^n \Gamma_n^{-1} \gamma_{n+1}^n$$

Proof:

$$\begin{aligned} P_{n+1}^n &= \mathbb{E}[(x_{n+1} - \alpha_{n+1}^{n,*} x)^2] = \mathbb{E}[(x_{n+1} - \gamma_{n+1}^n \Gamma_n^{-1} x)^2] \\ &= \mathbb{E}[x_{n+1}^2 - 2\gamma_{n+1}^n \Gamma_n^{-1} x x_{n+1} + \gamma_{n+1}^n \Gamma_n^{-1} x x' \Gamma_n^{-1} \gamma_{n+1}^n] \\ &= \gamma(0) - 2\gamma_{n+1}^n \Gamma_n^{-1} \gamma_{n+1}^n + \gamma_{n+1}^n \Gamma_n^{-1} \Gamma_n \Gamma_n^{-1} \gamma_{n+1}^n \\ &= \gamma(0) - \gamma_{n+1}^n \Gamma_n^{-1} \gamma_{n+1}^n. \end{aligned}$$

- The **Durbin-Levinson Algorithm** (Property 3.2) solves  $\alpha_{n+1}^{n,*}$  and  $P_{n+1}^n$  recursively.

## One-Step Ahead Forecasting for $\text{AR}(p)$

- **Example 3.19:** One-step ahead forecasting with causal  $\text{AR}(2)$

$$x_t = \phi_1 x_{t-1} + \phi_2 x_{t-2} + w_t:$$

- Based on  $x_1, x_2, \dots$

$$\alpha_{n+1,n}^{n,*} = \Gamma_n^{-1} \gamma_{n+1}^n,$$

$$\alpha_{n+1,n}^{n,*} = \phi_1, \quad \alpha_{n+1,n-1}^{n,*} = \phi_2, \quad \alpha_{n+1,k}^{n,*} = 0, \quad k \geq n-2.$$

- Obvious generalization to  $\text{AR}(p)$ .
- Asymptotic relation to  $\pi$  weights

$$\lim_{n \rightarrow \infty} \alpha_{n+1,n-k}^{n,*} = -\pi_k, \quad k = 1, 2, \dots, n$$

## $m$ -step Ahead Forecasting

- $m$ -step ahead prediction error satisfies

$$P_{n+m}^n \equiv \mathbb{E} [(x_{n+m} - x_{n+m}^n)^2] = \gamma(0) - \gamma'_{n+m} \Gamma_n \gamma_{n+m}^n$$

- **Prediction intervals:**

$$x_{n+m}^n \pm c_{\alpha/2} \sqrt{P_{n+m}^n}, \quad \Pr(|w_t| \geq c_{\alpha/2}) \leq \alpha$$

(need adjustment for multiple testing to get PI for more than one time period).

- **Example:** For **AR(1)** we have

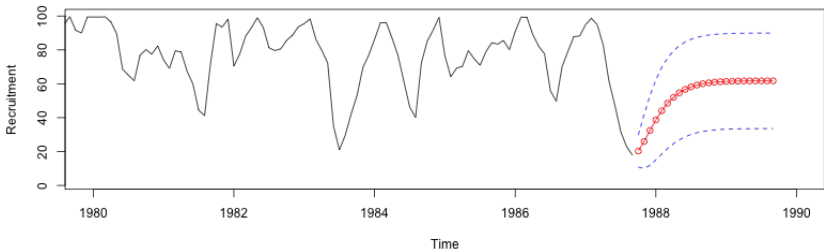
$$P_{n+1}^n = \sigma_w^2.$$

- **Example:** Long-range prediction

$$\lim_{m \rightarrow \infty} P_{n+m}^n = \gamma_x(0).$$

## Forecasting – Example 3.26

```
regr = ar.ols(rec, order=2, demean=FALSE, intercept=TRUE)
fore = predict(regr, n.ahead=24)
ts.plot(rec, fore$pred, col=1:2, xlim=c(1980,1990), ylab="Recruitment")
lines(fore$pred, type="p", col=2)
lines(fore$pred+fore$se, lty="dashed", col=4)
lines(fore$pred-fore$se, lty="dashed", col=4)
```



## Estimating ARMA parameters

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- For an **ARMA**( $p, q$ ) model with **all parameters given**, we know:
  - Theoretical properties (invertibility, causality).
  - Description of second moments (ACF and PACF).
  - Predict future observations.
  
- Next:
  - **Estimate ARMA**( $p, q$ ) **parameters** given  $p$  and  $q$  under invertibility and causality assumptions.
  - Later: How to find  $p$  and  $q$ ?
  - Later: Is **ARMA** even a good model?



Three techniques:

1. Method of moments (MoM) and Yule-Walker estimates
2. Conditional Least Squares (C-LS)
3. Maximum Likelihood (ML)

- Use

$$\hat{\mu} = \bar{x} \equiv \frac{1}{n} \sum_{j=1}^n x_j.$$

- **Theorem A.5:** If  $x_t$  is a linear process and  $\sum_j \psi_j \neq 0$ , then

$$\sqrt{n}(\bar{x}_n - \mu) \xrightarrow{d} \mathcal{N}(0, V), \quad V = \sum_{h=-\infty}^{\infty} \gamma_x(h) = \sigma_w^2 \left( \sum_{j=-\infty}^{\infty} \psi_j \right)^2.$$

- Henceforth assume  $\mu = 0$ .

## MoM II: Estimating AR( $p$ ) Parameters Yule-Walker Equations

- **Definition:** The **Yule-Walker equations** are

$$\begin{aligned}\gamma(h) &= \phi_1\gamma(h-1) + \dots + \phi_p\gamma(h-p), & h = 1, 2, \dots, p, \\ \sigma_w^2 &= \gamma(0) - \phi_1\gamma(1) - \dots - \phi_p\gamma(p).\end{aligned}$$

- In matrix notation

$$\Gamma_p \phi = \gamma_p, \quad \sigma_w^2 = \gamma(0) - \phi' \gamma_p,$$

$$\Gamma_p = \{\gamma(k-j)\}_{j,k=1}^p, \quad \phi = (\phi_1, \dots, \phi_p), \quad \gamma_p = (\gamma(1), \dots, \gamma(p))'$$

- **Method of moments** estimation (Yule-Walker estimators): Solve

$$\hat{\phi} = \hat{\Gamma}_p^{-1} \hat{\gamma}_p, \quad \hat{\sigma}_w^2 = \hat{\gamma}(0) - \hat{\gamma}_p' \hat{\Gamma}_p^{-1} \hat{\gamma}_p.$$

where

$$\hat{\Gamma}_p = \{\hat{\gamma}(k-j)\}_{j,k=1}^p, \quad \hat{\gamma}_p = (\hat{\gamma}(1), \dots, \hat{\gamma}(p))'.$$

- We can calculate  $\hat{\phi}$  without inverting  $\hat{\Gamma}_p$  using the **Durbin-Levinson algorithm**.

- **Property 3.8:** For a causal **AR**( $p$ ) process, as  $n \rightarrow \infty$ ,

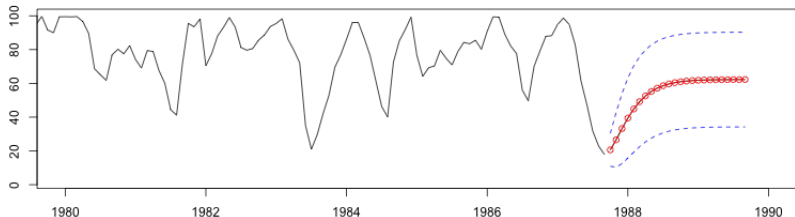
$$\sqrt{n}(\hat{\phi} - \phi) \xrightarrow{d} \mathcal{N}(0, \sigma_w^2 \mathbf{\Gamma}_p^{-1}), \quad \hat{\sigma}_w^2 \xrightarrow{P} \sigma_w^2.$$

# YW Estimation of the Recruitment Series

```
rec.yw = ar.yw(rec, order=2)
rec.yw$x.mean # = 62.26278 (mean estimate)
rec.yw$ar     # = 1.3315874, -.4445447 (parameter estimates)
sqrt(diag(rec.yw$asy.var.coef)) # = .04222637, .04222637 (standard errors)
rec.yw$var.pred # = 94.79912 (error variance estimate)
```

Predicting using estimated **AR(2)** parameters:

```
rec.pr = predict(rec.yw, n.ahead=24)
U = rec.pr$pred + rec.pr$se
L = rec.pr$pred - rec.pr$se
minx = min(rec,L); maxx = max(rec,U)
ts.plot(rec, rec.pr$pred, xlim=c(1980,1990), ylim=c(minx,maxx))
lines(rec.pr$pred, col="red", type="o")
lines(U, col="blue", lty="dashed")
lines(L, col="blue", lty="dashed")
```



### Example 3.29:

- Consider

$$x_t = w_t + \theta w_{t-1}, \quad |\theta| < 1.$$

- Recall  $\gamma_x(0) = \sigma_w^2(1 + \theta^2)$  and  $\gamma_x(1) = \sigma_w^2\theta$ . An estimator  $\hat{\theta}$  for  $\theta$  is obtained from

$$\hat{\rho}_x(1) = \frac{\hat{\gamma}_x(1)}{\hat{\gamma}_x(0)} = \frac{\hat{\theta}}{1 + \hat{\theta}^2}.$$

Two solutions exist. **We pick the invertible one.**

- If  $|\hat{\rho}_x(1)| \leq 1/2$ ,

$$\hat{\theta} = \frac{1 - \sqrt{1 - 4\hat{\rho}_x(1)^2}}{2\hat{\rho}_x(1)}$$

and (using the Delta Method)

$$\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{d} \mathcal{N}\left(0, \frac{1 + \theta^2 + 4\theta^4 + \theta^6 + \theta^8}{(1 - \theta^2)^2}\right).$$

- If  $|\hat{\rho}_x(1)| > 1/2$ , **a real solution does not exist.**
- Later:** The ML estimator has a better large sample behavior.

- **Definition: Maximum Likelihood (ML) Estimator**

1. Write likelihood function in terms of model parameters

$$L(\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q, \sigma_w^2) = L(x_1, \dots, x_n; \phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q, \sigma_w^2)$$

2. Solve

$$\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\theta}_1, \hat{\theta}_q, \hat{\sigma}_w^2 \operatorname{argmin} L(\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q, \sigma_w^2).$$

## Example: (conditional) ML Estimation of AR(1)

$$x_t = \phi x_{t-1} + w_t, \quad |\phi| < 1, \quad w_t \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_w^2).$$

- Likelihood function (conditioned on  $x_1$ )

$$L(\phi, \sigma_w^2) = f(x_1, \dots, x_n; \phi, \sigma_w^2) = \prod_{j=2}^n f(x_j | x_{j-1}; \phi, \sigma_w^2),$$

where

$$f(x_j | x_{j-1}; \phi, \sigma_w^2) = \frac{1}{\sqrt{2\pi\sigma_w^2}} \exp \left\{ - (x_j - \phi x_{j-1})^2 / \sigma_w^2 \right\}, \quad j = 2, \dots, n$$

- ML estimate

$$\hat{\phi} = \operatorname{argmin}_{\phi < 1} S_x(\phi; \mathbf{x}_1), \quad \hat{\sigma}_w^2 = S(\hat{\phi}) / (n - 1),$$

where

$$S_c(\phi; \mathbf{x}_1) \equiv \sum_{j=2}^n (x_j - \phi x_{j-1})^2.$$



- **Definition:** Conditional Least Squares Estimator for **ARMA**( $p, q$ )

1. Set  $\hat{w}_t = 0$  for  $t \leq p$ .
2. Write

$$\hat{w}_t = x_t - \phi_1 x_{t-1} - \dots - \phi_p x_{t-p} - \theta_1 \hat{w}_{t-1} - \dots - \theta_q \hat{w}_{t-q}, \quad t = p+1, \dots, n.$$

$$S_c(\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q) \equiv \sum_{t=p+1}^n \hat{w}_t^2.$$

3. Solve linear regression

$$\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\theta}_1, \dots, \hat{\theta}_q = \operatorname{argmin} S_c(\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q).$$

4. Set

$$\hat{\sigma}_w^2 \equiv \frac{1}{n-p-q} S_c(\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\theta}_1, \dots, \hat{\theta}_q)$$

- For **AR**(1), C-LS is almost identical to ML.

## Example: Fitting AR(2) to Recruitment

### Example 3.31

```
rec.mle = ar.mle(rec, order=2) rec.mle$x.mean  
rec.mle$ar  
sqrt(diag(rec.mle$asy.var.coef))  
rec.mle$var.pred
```

```
62.2615261054892  
1.35128085590502 -0.461273619173842  
0.0409915944162095 0.0409915944162095  
89.3359654276631
```

Compare with YW equations in [Example 3.28](#):

```
rec.yw = ar.yw(rec, order=2)  
rec.yw$x.mean  
rec.yw$ar  
sqrt(diag(rec.yw$asy.var.coef))  
rec.yw$var.pred
```

```
62.2627816777042  
1.33158738866791 -0.444544697634474  
0.0422263743755033 0.0422263743755033  
94.7991188417802
```

## Fitting AR(2) to Recruitment (cont'd)

Compare with C-LS in [Example 3.18](#):

```
fit <- ar.ols(rec , order=2, demean=TRUE , intercept=TRUE)
fit$x.mean
fit$ar
fit$asy.se.coef$ar
fit$var.pred
```

```
62.2627816777042
1.35406847266143 -0.46317843167489
0.041789006654309 0.0418794219793695
89.71705
```

# Large Sample Distribution

**Property 3.10:** Consider a causal invertible **ARMA**( $p, q$ ) process. Denote

$$\beta = (\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q).$$

Under appropriate conditions, C-LS estimate and ML estimate, all provide **asymptotically optimal** estimates  $\hat{\beta}$  of  $\beta$  and  $\hat{\sigma}_w^2$  of  $\sigma_w^2$ . In particular

$$\sqrt{n} \left( \hat{\beta} - \beta \right) \xrightarrow{d} \mathcal{N} \left( 0, \sigma_w^2 \Gamma_{p,q}^{-1} \right), \quad \Gamma_{p,q} \equiv \begin{pmatrix} \Gamma_{\phi\phi} & \Gamma_{\phi\theta} \\ \Gamma_{\theta\phi} & \Gamma_{\theta\theta} \end{pmatrix},$$

Where:

- $\Gamma_{\phi\phi} \equiv \{\gamma_x(i-j)\}_{i,j=1}^p$  where  $\gamma_x(h)$  is the autocovariance of **AR**( $p$ )  
 $\phi(B)x_t = w_t$
- $\Gamma_{\theta\theta} \equiv \{\gamma_y(i-j)\}_{i,j=1}^q$  where  $\gamma_y(h)$  is the autocovariance of the **MA**( $q$ )  $y_t = \theta(B)w_t$ .
- $\Gamma_{\phi\theta} \equiv \{\gamma_{xy}(i-j)\}_{i,j=1}^{p,q}$  where  $\gamma_{xy}(h)$  is the crosscovariance of  $x_t$  and  $y_t$ .
- $\Gamma_{\theta\phi} = \Gamma'_{\phi\theta}$ .

## Specific Asymptotic Distributions

- **AR(1):**

$$\sqrt{n}(\hat{\phi} - \phi) \xrightarrow{d} \mathcal{N}(0, 1 - \phi^2).$$

- **AR(2):**

$$\sqrt{n} \left( \begin{pmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \end{pmatrix} - \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} \right) \xrightarrow{d} \mathcal{N} \left( 0, \begin{pmatrix} 1 - \phi_2^2 & -\phi_1(1 + \phi_2) \\ -\phi_1(1 + \phi_2) & 1 - \phi_2^2 \end{pmatrix} \right)$$

- **MA(1):**

$$\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{d} \mathcal{N}(0, 1 - \theta^2)$$

- **ARMA(1, 1):**

$$\sqrt{n} \left( \begin{pmatrix} \hat{\phi} \\ \hat{\theta} \end{pmatrix} - \begin{pmatrix} \phi \\ \theta \end{pmatrix} \right) \xrightarrow{d} \mathcal{N} \left( 0, \begin{pmatrix} (1 - \phi_2^2)^{-1} & (1 + \phi\theta)^{-1} \\ (1 + \phi\theta)^{-1} & (1 - \theta^2)^{-1} \end{pmatrix}^{-1} \right)$$

Note: Variance inflation due to fitting **AR(2)** to **AR(1)**.

# Recap

- **ARMA**( $p, q$ ) is a useful model for **stationary processes**.
- We can express **ACF** and **optimal linear  $m$ -step forecast** in terms of model's parameters.
- We can **fit ARMA**( $p, q$ ) **to data** using several techniques. Leading to asymptotically normal estimators.

Next:

- Extensions (ARIMA, SARIMA)
- How to select  $p$  and  $q$ ?
- Is **ARMA** a good model for my data?