

STATS 207: Time Series Analysis

Autumn 2020

Lecture 3: Sample ACF; Time-Series regression

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ESTIMATING AUTO- AND CROSSCOVARIANCE

CLASSICAL REGRESSION

MODEL COMPLEXITY & NESTED MODELS

SINUSOIDAL REGRESSION

- Home assignment 1 is out. It is Due two weeks later (Monday 10/5/2020).
- Slides and recordings of lectures 1 and 2 are available on Canvas.
- You will have the option to drop the final exam/assessment from the final grade.

Estimating Auto- and Crosscovariance

Recap: Autocovariance

- *Autocovariance function*

$$\gamma_x(t+h, t) \equiv \mathbb{E} [(x_{t+h} - \mu_{x(t+h)})(x_t - \mu_{xt})]$$

- *Sample autocovariance function*

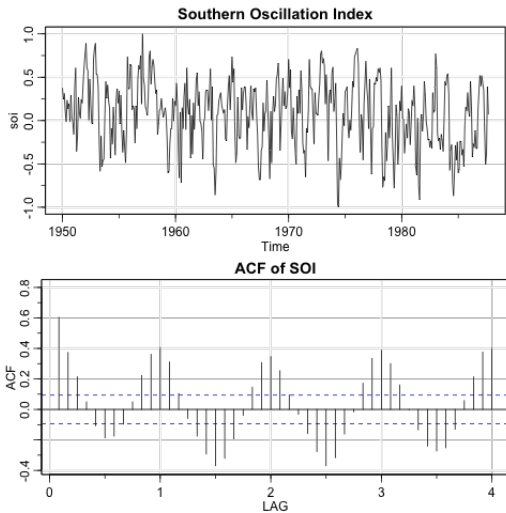
$$\hat{\gamma}_x(h) \equiv \frac{1}{n} \sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(x_t - \bar{x}).$$

- (x_t) is stationary if $\mu_{xt} = \mu$ and $\gamma_x(t+h, t)$ is only a function of h , say $\gamma_x(h)$.
- Under stationarity assumption,

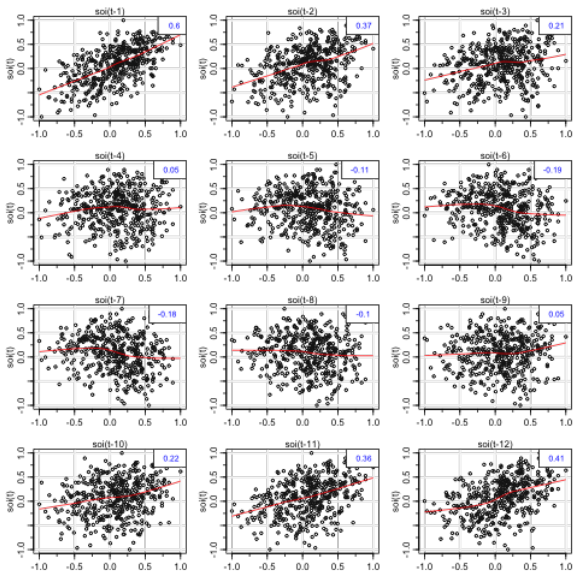
$$\hat{\gamma}_x(h) \rightarrow \gamma_x(h) \quad (LLN).$$

- Similar result holds for the autocorrelation $\rho_x(h)$ and sample autocorrelation $\hat{\rho}_x(h)$.

Example: Southern Oscillation Index (SOI)



Southern Oscillation Index (SOI) Scatter Plot



Recap: Crosscovariance

- *Crosscovariance function*

$$\gamma_{xy}(t+h, t) \equiv \mathbb{E} [(x_{t+h} - \mu_{x(t+h)})(y_t - \mu_{yt})]$$

- *Sample crosscovariance function*

$$\hat{\gamma}_{xy}(h) \equiv \frac{1}{n} \sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(y_t - \bar{y}).$$

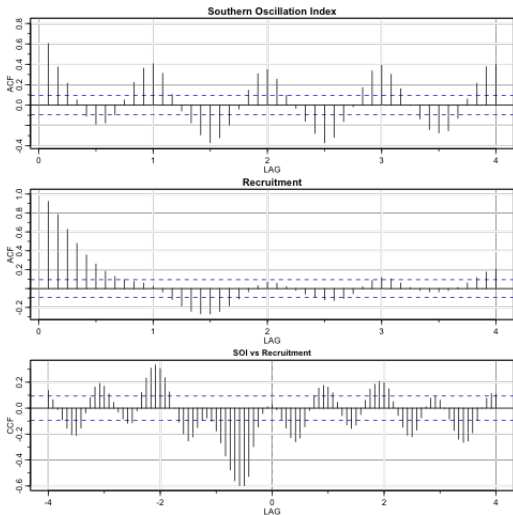
- $(x_t), (y_t)$ are jointly stationary if both are stationary and $\gamma_{xy}(t+h, t)$ is only a function of h , say $\gamma_{xy}(h)$.
- Under joint stationarity assumption,

$$\hat{\gamma}_{xy}(h) \rightarrow \gamma_{xy}(h) \quad (LLN).$$

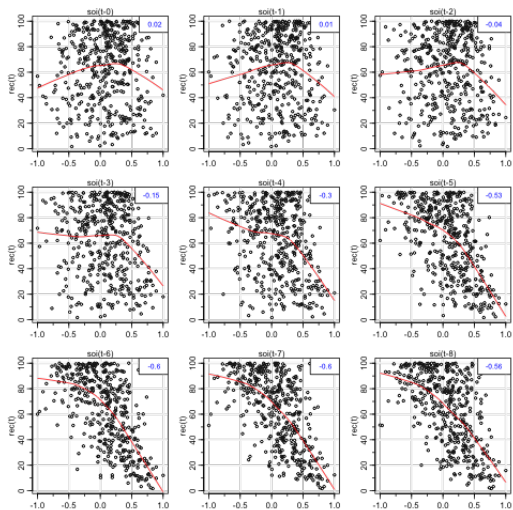
- Similar result holds for the crosscorrelation $\rho_{xy}(h)$ and sample crosscorrelation $\hat{\rho}_{xy}(h)$.

Example: CCF of SOI/Recruitment Data

Example 1.28 in [\[Shumway & Stoffer\]](#)



SOI/Recruitment Scatter Plot



Confidence Limits for Autocovariance

For white noise (w_t):

- Sample autocorrelation:

$$\text{SE} [\hat{\rho}_w(h)] \approx \frac{1}{\sqrt{n}}.$$

- Sample cross-correlation:

$$\text{SE} [\hat{\rho}_{wx}(h)] \approx \frac{1}{\sqrt{n}},$$

where (x_t) is independent of (w_t).

(approximations assume $h \ll n$)

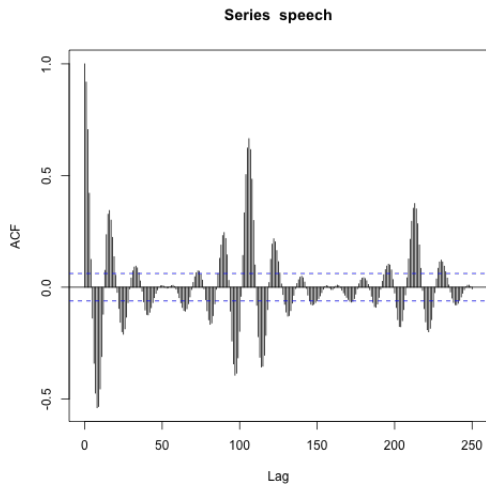
- From the CLT (Theorem A.7 and Property P1.1 in [\[Shumway & Stoffer\]](#)): for $h > 0$,

$$\Pr (|\hat{\rho}_w(h)| > 1.96/\sqrt{n}) \approx \Pr (|\mathcal{N}(0, 1)| > 1.96) = 0.05.$$

$$\Pr (|\hat{\rho}_{wx}(h)| > 1.96/\sqrt{n}) \approx \Pr (|\mathcal{N}(0, 1)| > 1.96) = 0.05.$$

ACF of Speech Data

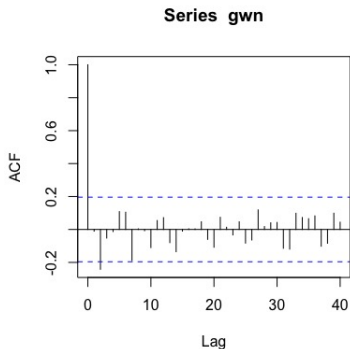
Example 1.27 in [\[Shumway & Stoffer\]](#)



Not a white noise!

Multiple Testing Warning

- If $|\hat{\rho}_x(h)| > 1.96n^{-1/2}$ for some $h > 0$, can we determine that (x_t) is not a white noise?



Classical Regression

Ordinary Least Squares (OLS) regression

- Linear regression model:

$$x_t = \beta_0 + \beta_1 z_{t1} + \dots, \beta_q z_{tq} + w_t.$$

- $\{\beta_j\}$ unknown fixed regression coefficients.
- (w_t) is white noise
- x_t dependent variable (to be predicted)
- $\{z_{tj}\}$ independent variables (predictors)
- Matrix notation:

$$x_t = \beta' \mathbf{z}_t + w_t$$

Example: Estimating Trend

Chicken price over time (Example 2.1):

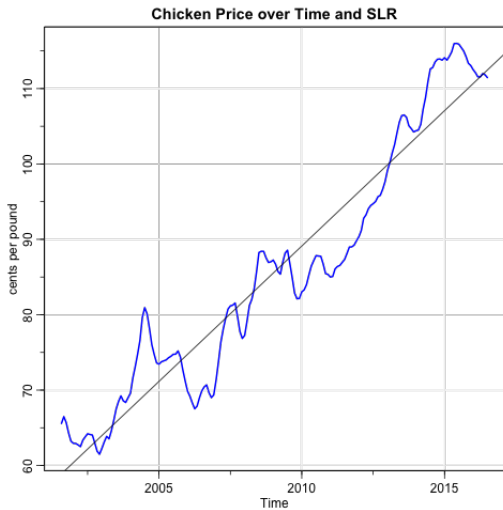
$$x_t = \beta_0 + \beta_1 z_t + w_t, \quad z_t = 2001 \frac{7}{12}, 2001 \frac{8}{12}, \dots, 2016 \frac{6}{12} \quad (180 \text{ months}).$$

- Regression model with $q = 1$
- OLS:

```
summary(fit <- lm(chicken~time(chicken))) # regress price on time
#Coefficients:
#           Estimate      Std. Error
# (Intercept) -7.131e+03    1.624e+02
# time(chicken)  3.592e+00    8.084e-02
```

- Interpretation: β_1 is the increment in price (cents) per month

Example 2.1



Terminal Output

```
Call: lm(formula = chicken ~ time(chicken))

Residuals:
    Min       1Q   Median       3Q      Max
-8.7411 -3.4730  0.8251  2.7738 11.5804

Coefficients:
                Estimate Std. Error t value Pr(>|t|)
(Intercept)  -7.131e+03  1.624e+02  -43.91  <2e-16 ***
time(chicken)  3.592e+00  8.084e-02   44.43  <2e-16 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 4.696 on 178 degrees of freedom
Multiple R-squared:  0.9173,    Adjusted R-squared:  0.9168
F-statistic: 1974 on 1 and 178 DF,  p-value: < 2.2e-16
```

OLS Matrix Notation/Formulas

$$x_t = \beta' \mathbf{z}_t + w_t$$

- \mathbf{z}_t is $q + 1$ -dimensional vector of predictors (features) at time t .
- $\beta = (\beta_0, \dots, \beta_q)'$ vector of regression coefficients
- LS estimator for β :

$$\hat{\beta} = \left(\sum_{t=1}^n \mathbf{z}_t \mathbf{z}_t' \right)^{-1} \sum_{t=1}^n \mathbf{z}_t x_t.$$

- Minimized error sum of squares:

$$\text{SSE} \equiv \text{SSE}_q \equiv \sum_{t=1}^n (x_t - \hat{\beta}' \mathbf{z}_t)^2.$$

(as an estimator to β , $\hat{\beta}$ is unbiased and has minimum variance over the class of unbiased estimators).

OLS Formulas (cont'd)

- An unbiased estimator for σ_w^2 :

$$s_w^2 \equiv \hat{\sigma}_w^2 \equiv \text{MSE} \equiv \frac{\text{SSE}}{n - (q + 1)}$$

(aka as *adjusted* sum of squares error).

- Assume that (w_t) is white Gaussian noise. Then

$$\hat{\beta} \sim \mathcal{N}(\beta, \sigma_w^2 \cdot C), \quad C = \left(\sum_{t=1}^n \mathbf{z}_t \mathbf{z}_t' \right)^{-1}.$$

Consequently,

$$t_i \equiv \frac{\hat{\beta}_i - \beta_i}{s_w \sqrt{C_{i,i}}} \text{ has a } t \text{ distribution with } n - (q + 1) \text{ DoF.}$$

($\beta_i = 0$ in output of `summary(fit)`)

Competing Models

- Suppose a competing model

$$x_t = \beta_0 + \beta_1 z_{t1} + \cdots + \beta_r z_{tr} + w_t, \quad r < q,$$

equivalently:

$$H_0 : \beta_{r+1} = \cdots = \beta_q = 0.$$

- Test the reduced model ($r + 1$ coefficients) against the full model ($q + 1$ coefficients):

$$F \equiv \frac{(\text{SSE}_r - \text{SSE}_q)/(q - r)}{\text{SSE}_q/(n - q - 1)}.$$

Under H_0 , $F \sim F_{n-q-1}^{q-r}$ (F distribution with $q - r$ DoF and $n - q - 1$ DoF)

- **Coefficient of determination:**

$$R^2 \equiv \frac{\text{SSE}_0 - \text{SSE}_q}{\text{SSE}_0}, \quad \text{SSE}_0 = \sum_{t=1}^n (x_t - \bar{x})^2,$$

(proportion of variation accounted for by all variables compared to the sum of squares error under the model $x_t = \beta_0 + w_t$).

Terminal Output

```
Call: lm(formula = chicken ~ time(chicken))

Residuals:
    Min       1Q   Median       3Q      Max
-8.7411 -3.4730  0.8251  2.7738 11.5804

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
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Residual standard error: 4.696 on 178 degrees of freedom
Multiple R-squared:  0.9173,    Adjusted R-squared:  0.9168
F-statistic: 1974 on 1 and 178 DF,  p-value: < 2.2e-16
```

Model Complexity & Nested Models

Overfitting

- In-sample MSE

$$\text{SSE}_k = \sum_{t=1}^n (x_t - \hat{\beta}' \mathbf{z}_t)^2$$

always decreases in the number of features k .

- **Consequence:** If you simply pick the model with the smallest SSE, it will always be the biggest model, even if the predictor are junk! aka **overfitting**.
- D. Donoho: “Overfitting is the biggest systematic validity problem in science.” (systematically claiming ‘structure’ that’s just noise). See also J. Ioannidis.
- The situation is similar with the adjusted SSE

$$\frac{\text{SSE}_k}{n - (k + 1)},$$

as the penalty in increasing k is not sever enough.

Complexity Penalization

- Ideology: we need more severe penalization than adjusted SSE.
- **Definition:** Akaike's Information Criterion (AIC):

$$\text{AIC}(k) \equiv \log \hat{\sigma}_k^2 + \frac{n + 2k}{n}, \quad \hat{\sigma}_k^2 \equiv \frac{\text{SSE}_k}{n},$$

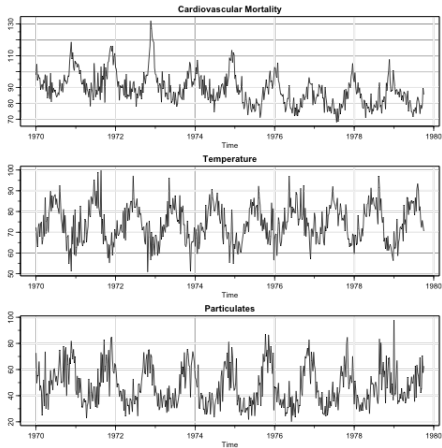
where k is the number of parameters in the model.

- Other criteria:

$$\text{AIC}_c(k) \equiv \log \hat{\sigma}_k^2 + \frac{n + k}{n - k - 2}; \quad \text{BIC}(k) \equiv \log \hat{\sigma}_k^2 + \frac{k \log(n)}{n}.$$

Pollution, Temperature and Mortality (Example 2.2)

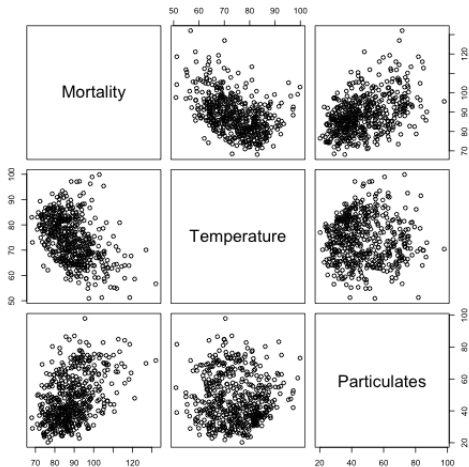
```
par(mfrow=c(3,1))  
tsplot(cmort, main="Cardiovascular Mortality", ylab="")  
tsplot(temp, main="Temperature", ylab="")  
tsplot(part, main="Particulates", ylab="")
```



508 six-day smoothed averages of daily values

Pollution, Temperature and Mortality (pairs plot)

```
pairs(cbind(Mortality=cmort, Temperature=tempr, Particulates=part))
```



Pollution, Temperature and Mortality (model fitting)

- (P)ollution, (T)emperature, (M)ortality
- Several models:

$$M_t = \beta_0 + \beta_1 t + w_t$$

$$M_t = \beta_0 + \beta_1 t + \beta_2(T_t - \bar{T})$$

$$M_t = \beta_0 + \beta_1 t + \beta_2(T_t - \bar{T}) + \beta_3(T_t - \bar{T})^2 + w_t$$

$$M_t = \beta_0 + \beta_1 t + \beta_2(T_t - \bar{T}) + \beta_3(T_t - \bar{T})^2 + \beta_4 P_t + w_t$$

Pollution, Temperature and Mortality (reg.stats)

```
reg.stats = function(fit){
  SSE = sum(fit$residuals^2);
  df = fit$df.residual
  response = fit$fitted.values+fit$residuals
  R.sq = 1 - sum(fit$residuals^2)/sum((response-mean(response))^2);
  model = paste(fit$call)[2]
  MSE = SSE/df
  n = length(fit$residuals)
  k = n - df
  AIC = log(MSE) + (n+2*k)/n
  BIC = log(MSE) + k*log(n)/n
  result = data.frame(k=k,SSE=SSE, df=df, MSE=MSE,
                      R.sq=R.sq, AIC=AIC, BIC=BIC)
  result
}
```

Pollution, Temperature and Mortality (output)

```
print(rbind(reg.stats(fit.2),
            reg.stats(fit.3),
            reg.stats(fit.4),
            reg.stats(fit.5)))
```

	k	SSE	df	MSE	R.sq	AIC	BIC
1	2	40019.84	506	79.09059	0.2104470	5.378468	4.395123
2	3	31413.21	505	62.20438	0.3802474	5.142236	4.167220
3	4	27984.53	504	55.52486	0.4478921	5.032579	4.065890
4	5	20508.44	503	40.77225	0.5953881	4.727687	3.769325

Best Model

```
| fit.5
```

```
Call:
```

```
lm(formula = cmort ~ trend + temp + temp2 + part)
```

```
Coefficients:
```

(Intercept)	trend	temp	temp2	part
2831.49025	-1.39590	-0.47247	0.02259	0.25535

- Negative trend in time.
- Negative trend for adjusted temperature.
- Quadratic effect can be seen from the pairs plot
- Pollution weights positively. Interpretation: “incremental contribution to daily deaths per unit of particulate pollution”.

Sinusoidal Regression

$$x_t = A \cos(2\pi\omega t + \phi) + w_t$$

- Linearization trick

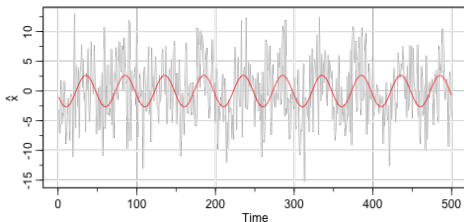
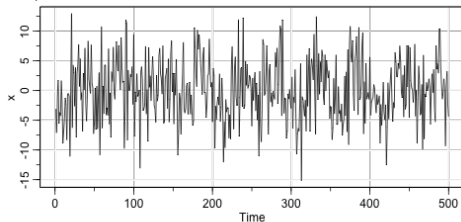
$$\beta_1 \cos(2\pi\omega t) + \beta_2 \sin(2\pi\omega t) = A \cos(2\pi\omega t + \phi)$$

- Fit using cos and sin:

$$x_t = \beta_1 \cos(2\pi\omega t) + \beta_2 \sin(2\pi\omega t) + w_t.$$

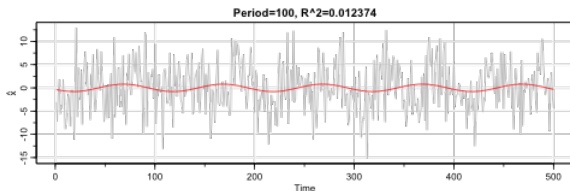
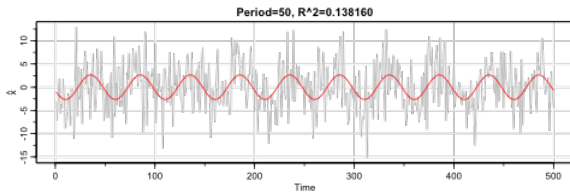
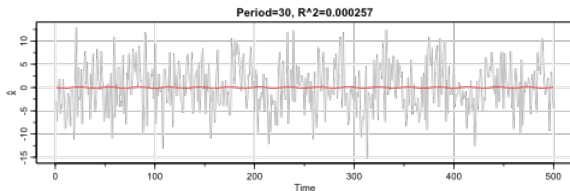
Example 2.10: Signal Hidden in Noise

```
set.seed(1000) # so you can reproduce these results
x = 2*cos(2*pi*1:500/50 + .6*pi) + rnorm(500,0,5)
z1 = cos(2*pi*1:500/50)
z2 = sin(2*pi*1:500/50)
summary(fit <- lm(x~0+z1+z2)) # zero to exclude the intercept
par(mfrow=c(2,1)); tsplot(x); tsplot(x, col=8, ylab=expression(hat(x)))
lines(fitted(fit), col=2)
```



How to Determine Periodicity?

- By Trial and Error:



How to Determine Periodicity?

- OLS regression coefficients

$$\hat{\beta}_1(j/n) = \frac{2}{n} \sum_{t=1}^n x_t \cos(2\pi jt/n), \quad \hat{\beta}_2(j/n) = \frac{2}{n} \sum_{t=1}^n x_t \sin(2\pi jt/n)$$

- Measure of power in fitted model at frequency $\omega = 2\pi j/n$:

$$P(j/n) \equiv \hat{\beta}_1^2(j/n) + \hat{\beta}_2^2(j/n)$$

- R^2 at frequency j :

$$R^2 = \frac{P(j/n)}{\sum_{i=1}^n P(j/n)}$$

Periodogram (Section 4.3)

- Discrete Fourier Transform (aka Fast Fourier Transform):

$$d(j/n) \equiv \frac{1}{\sqrt{n}} \sum_{t=1}^n x_t e^{-2\pi\sqrt{-1}tj/n}, \quad j = 0, \dots, n-1.$$

- Commutable in $O(n \log(n))$ flops (when $n = 2^k$)
- **Definition:** *Periodogram*

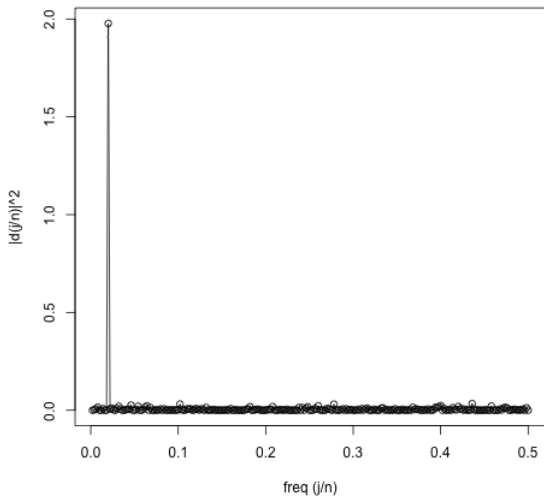
$$I(j/n) \equiv |d(j/n)|^2.$$

- Measure of power in fitted model at frequency $\omega = 2\pi j/n$:

$$P(j/n) = \frac{4}{n} I(j/n).$$

Periodogram

```
x = 2*cos(2*pi*1:500/50 + .6*pi) + rnorm(500,0,5)
s = spectrum(x, plot=FALSE)
plot(s$freq, abs(s$spec/500)^2, ylab="|d(j/n)|^2", type="ol",
      xlab='freq (j/n)')
```



Fisher's Periodogram Test (Fisher's G-test)

- Test

H_0 : white noise

H_1 : signal plus noise

- Statistic:

$$F = \max_j \frac{I(j/n)}{\sum_{i=1}^n I(i/n)}.$$

- Reject H_0 for large values of F :

$$F \geq c_\alpha, \quad c_\alpha \approx K(\alpha) \log(n)/n.$$

```
set.seed(1000)
w = rnorm(500,0,5)
print(fisher.g.test(w))
print(fisher.g.test(2*cos(2*pi*1:500/50 + .6*pi) + w))
```

```
[1] 0.1486071
[1] 2.310001e-14
```